

# Credible Monetary Policy in an Infinite Horizon Model: Recursive Approaches

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October 20th, 2010

# Introduction

This paper develops a recursive method to study optimal policy in a dynamic model.

- Ramsey policy
- Sustainable policy

Two key ingredients:

- Finding appropriate state variables.
- Defining an appropriate operator.

- A representative household:
  - $\sum_{t=0}^{\infty} \beta^t [u(c_t) + v(m_t^H)], m_t^H \equiv q_t M_t^H.$
  - HBC:  $c_t + q_t M_t^H \leq y_t - x_t + q_t M_{t-1}^H, m_t^H \in [0, \bar{m}] \equiv M.$
  - $y_t = f(x_t)$
  - $M_{-1}^H = M_{-1}$  given.
- Government:
  - GBC:  $-x_t = q_t (M_t^G - M_{t-1}^G)$
  - $M_{-1}^G = M_{-1}$  given.
  - $h_t \equiv M_{t-1}^G / M_t^G$
  - $h_t \in [\underline{h}, \bar{h}] \equiv H (\Rightarrow x_t \in X)$
- Notation:  $\mathbf{z} \equiv \{z_t\}_{t=0}^{\infty}, \mathbf{z}^t \equiv \{z_s\}_{s=0}^t,$  and  $\mathbf{z}_t \equiv \{z_s\}_{s=t}^{\infty}$  for any  $z.$

# A Competitive Equilibrium

Proposition: A competitive equilibrium is characterized by a sequence  $(\mathbf{m}, \mathbf{x}, \mathbf{h})$  such that, for all  $t$ ,  $m_t \in M$ ,  $x_t \in X$ ,  $h_t \in H$ , and

$$\begin{aligned}x_t &= m_t(h_t - 1) \\m_t[u'[f(x_t)] - v'(m_t)] &\leq \beta u'[f(x_{t+1})](m_{t+1} + x_{t+1}), \text{ (} = \text{ if } m_t < \bar{m}) \\ &\equiv \beta \theta_{t+1}\end{aligned}$$

$\theta_t$ : “promised marginal utility”

Notation:  $CE \equiv \{(\mathbf{m}, \mathbf{x}, \mathbf{h}) \mid \text{the conditions above hold.}\}$

# Ramsey Plan: A Standard Formulation

$$V^R = \max_{(m,x,h) \in CE} \sum_{t=0}^{\infty} \beta^t [u[f(x_t)] + v(m_t)]$$

# Ramsey Plan: A Recursive Formulation

Let

$$\Omega \equiv \{\theta \in \mathbb{R} : \theta = u'[f(x_0)](m_0 + x_0) \text{ for some } (\mathbf{m}, \mathbf{x}, \mathbf{h}) \in CE\}$$

$$\Gamma(\theta) \equiv \{(\mathbf{m}, \mathbf{x}, \mathbf{h}) \in CE : \theta = u'[f(x_0)](m_0 + x_0)\}$$

We can write the Ramsey problem in two steps:

$$w^*(\theta) = \max_{(\mathbf{m}, \mathbf{x}, \mathbf{h}) \in \Gamma(\theta)} \sum_{t=0}^{\infty} \beta^t [u[f(x_t)] + v(m_t)]$$

$$V^R = \max_{\theta \in \Omega} w^*(\theta)$$

# Ramsey Plan: A Recursive Formulation

Proposition:  $w^*(\theta)$  satisfies the functional equation:

$$w(\theta) = \max_{(m,x,h,\theta')} u[f(x)] + v(m) + \beta w(\theta')$$

s.t.

$$(m, x, h, \theta') \in M \times X \times H \times \Omega$$

$$\theta = u'[f(x)](m + x)$$

$$x = m(h - 1)$$

$$m[u'[f(x)] - v'(m)] \leq \beta\theta', = \text{if } m < \bar{m}$$

Conversely, if a bounded function  $w : \Omega \rightarrow \mathbb{R}$  satisfies the above functional equation, then  $w = w^*$

# Ramsey Plan: Finding $\Omega$

An operator on  $\mathbb{B}$ : For any  $Q \subseteq \mathbb{R}$ , define a new set  $\mathbb{B}(Q)$  as follows.

$$\begin{aligned}\mathbb{B}(Q) = \{ & \theta \in \mathbb{R} \mid \\ & \exists (m, x, h, \theta') \in M \times X \times H \times Q \text{ such that} \\ & \theta = u'[f(x)](m + x) \\ & x = m(h - 1) \\ & m[u'[f(x)] - v'(m)] \leq \beta\theta', = \text{if } m < \bar{m}\}\end{aligned}$$

Prop. 1: If  $Q \subseteq \mathbb{B}(Q)$ , then  $\mathbb{B}(Q) \subseteq \Omega$

Prop. 2:  $\Omega = \mathbb{B}(\Omega)$

Prop. 3: Let  $Q_0 = [0, \bar{\theta}]$ . Let  $Q_n = \mathbb{B}(Q_{n-1})$ . Then,  $Q_n \supseteq Q_{n+1}$  and  $\Omega = \bigcap_{n=0}^{\infty} Q_n$ .



# Sustainable Plan: Set-Up (1)

A government strategy,  $\sigma \equiv \{\sigma_t\}_{t=0}^{\infty}$

- $\sigma_0 \in H$
- $\sigma_t : H^{t-1} \rightarrow H$  (i.e.,  $h_t = \sigma_t(\mathbf{h}^{t-1})$ )

An allocation strategy,  $\alpha \equiv \{\alpha_t\}_{t=0}^{\infty}$

- $\alpha_t : H^t \rightarrow M \times X$  (i.e.,  $(m_t, x_t) = \alpha_t(\mathbf{h}^t)$ )

Remarks:

- $(\sigma, \alpha)$  induces an outcome  $(\mathbf{m}, \mathbf{x}, \mathbf{h})$ .
- $(\sigma, \alpha)$  implies a value,  $w = \sum_{t=0}^{\infty} \beta^t [u[f(x_t)] + v(m_t)]$ , and an initial promised MU,  $\theta = u'[f(x_0)](m_0 + x_0)$ .
- After any history  $\mathbf{h}^{t-1}$ , the continuation of a strategy is also a strategy.

## Sustainable Plan: Set-Up (2)

Let  $CE_H \equiv \{\mathbf{h} \in H^\infty \mid \exists(\mathbf{m}, \mathbf{x}) \text{ such that } (\mathbf{m}, \mathbf{x}, \mathbf{h}) \in CE\}$

Definition:  $\sigma$  is admissible if, after any history  $\mathbf{h}^{t-1}$ ,  $\mathbf{h}_t$  induced by the continuation of  $\sigma$  belongs to  $CE_H$

Definition: Given  $\sigma$ ,  $\alpha$  is competitive if, after any history  $\mathbf{h}^t$ , the continuation of  $\alpha$  and  $\sigma$  induce a  $(\mathbf{m}, \mathbf{x}, \mathbf{h}) \in CE$ .

# Sustainable Plan: Definition

Definition:  $(\sigma, \alpha)$  is a sustainable plan if

- $\sigma$  is admissible.
- $\alpha$  is competitive given  $\sigma$ .
- After any history  $\mathbf{h}^{t-1}$ , the sequence  $\mathbf{h}_t$  induced by  $\sigma$  maximizes the household's utility over  $CE_H$  given  $\alpha$ .

Definition:  $(\mathbf{m}, \mathbf{x}, \mathbf{h})$  is a sustainable outcome if it is induced by a sustainable plan.

Remark: After any history  $\mathbf{h}^{t-1}$ , the continuation of a sustainable plan is itself a sustainable plan.

$$S \equiv \{(w, \theta) | \exists \text{ a sustainable outcome } (\mathbf{m}, \mathbf{x}, \mathbf{h}) \\ \text{with value } w \text{ and } u'[f(x_0)](m_0 + x_0) = \theta\}$$

# Sustainable Plan: Finding S (1)

Take a sustainable plan with a particular value of  $w$  and  $\theta$ .

$$(1) \quad w = u[f(x(h^*))] + v[m(h^*)] + \beta w'(h^*)$$

$$\geq u[f(x(h))] + v[m(h)] + \beta w'(h) \quad \forall h$$

$$(2) \quad \theta = u'[f(x(h^*))](m(h^*) + x(h^*))$$

$$(3) \quad x(h) = m(h)(h - 1) \quad \forall h$$

$$(4) \quad m(h)[u'[f(x(h))] - v'(m(h))] \leq \beta \theta'(h) \quad (, = \text{ if } m(h) < \bar{m}) \quad \forall h$$

$(w'(h), \theta'(h))$  must belong to S for all  $h$ .

## Sustainable Plan: Finding $S$ (2)

An operator  $\mathbb{D}$ : For any set  $Z \subseteq \mathcal{W} \times \Omega$ , define a new set  $\mathbb{D}(Z)$  as follows.

$$\begin{aligned} \mathbb{D}(Z) = & \{(w, \theta) \mid \\ & \exists h^* \text{ and} \\ & (m(h), x(h), w'(h), \theta'(h)) \in M \times X \times Z \text{ for all } h \\ & \text{such that (1), (2), (3), and (4) hold.}\} \end{aligned}$$

Prop. 1: If  $Z \subseteq \mathbb{D}(Z)$ , then  $\mathbb{D}(Z) \subseteq S$

Prop. 2:  $S = \mathbb{D}(S)$

Prop. 3: Let  $Z_0 = \mathcal{W} \times \Omega$ , and  $Z_n = \mathbb{D}(Z_{n-1})$ . Then,  $S = \bigcap_{n=0}^{\infty} Z_n$ .