

On Efficient Distribution with Private Information

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The model

- Discrete time, infinite horizon $t = 0, 1, 2, \dots$
- Single, non storable good
- Continuum of consumers (measure 1):

- Preferences

$$E \left(\sum_{t=0}^{\infty} (1 - \beta) \beta^t V(c_t) \theta_t \right)$$

where $V' > 0$, $V'' < 0$

- Idiosyncratic, serially independent, iid taste shock:
 $\theta_t \in \Theta = \{\theta_1, \dots, \theta_n\}$, and

$$\Pr(\theta_t = \theta_i) = \mu(\theta_i) \text{ for all } i \text{ and all } t$$

- Idiosyncratic taste shocks are private information of the consumers.

Endowments

- Endowment economy: Fixed aggregate endowment y in every period.
- Each consumer enters the economy with a number $w \in D \subset \mathbb{R}$ which can be thought of as his initial entitlement to expected, discounted utility.
- Distribution of utilities:

$$\Pr(w \in A) = \psi(A) \text{ for all } A \subseteq D$$

Fraction of people in the economy with $w \in A$. $\psi \in M$, where M is the set of all probability measures on (D, \mathbf{D}) where \mathbf{D} are the Borel subsets of D .

Planner's Objective

Use the minimum amount of resources (as constant, perpetual, endowment flow) to attain a certain distribution ψ given the information available.

Reporting Strategies

A **reporting strategy** is a sequence $z = \{z_t(\theta^t)\}_{t=0}^{\infty}$,
 $z_t : \Theta^{t+1} \rightarrow \Theta$

A **truthful** reporting strategy is a reporting strategy
 $z^* = \{z_t^*(\theta^t)\}_{t=0}^{\infty}$ such that $z_t^*(\theta^t) = \theta_t$ for all t and all
 $\theta^t \in \Theta^{t+1}$

- Reporting history: $z^t = \{z_0(\theta_0), \dots, z_t(\theta_t)\}$

Plan

Let, $u_t(w, z^t) = V(c_t(w, z^t))$, $u_t : D \times \Theta^{t+1} \rightarrow \mathbb{R}$

A **plan** is a sequence $u = \{u_t(w, z^t)\}_{t=0}^{\infty}$ such that

$$\lim_{t \rightarrow \infty} \beta^t \sum_{s=0}^{\infty} \beta^s u_{t+s}(w, z^{t+s}) \theta_{t+s} = 0$$

\implies Discounted expected lifetime utility of plan u and reporting strategy z

$$U(w, u, z) \equiv E \left(\sum_{t=0}^{\infty} (1 - \beta) \beta^t u(w, z^t) \theta_t \right)$$

Allocation

A plan u is an **allocation** if it satisfies

- Truth Telling: given u truth telling is optimal for the agents

$$U(w, u, z^*) \geq U(w, u, z) \quad \text{for all } z \in Z \text{ and all } w \in D$$

- Promise keeping: u delivers the expected discounted utility to each agent w

$$U(w, u, z^*) = w \text{ for all } w$$

Efficiency

An allocation is **efficient** if it attains a distribution ψ at the minimum cost (as constant, perpetual, endowment flow) of attaining ψ .

Planner's Problem

Objective: Minimize constant stream of endowment to attain a welfare distribution ψ .

$$\min_u y$$

such that

- u is an allocation
- u attains ψ with resources y , i.e.,

$$\int_{D \times \Theta} C(u_t(w, \theta^t)) d\mu(\theta_t) d\psi(w) \leq y \quad \text{for all } t$$

where $C(u_t(w, z^t)) \equiv c_t(w, z^t)$ (inverse function of V)

Allocation rule

Let $f_t(w_t, z^{t-1}, z_t) = u_t(w_t, z^t)$, $g_t(w_t, z_t) = w_{t+1}$

A sequence $\sigma = \{f_t, g_t\}_{t=0}^{\infty}$ is an **allocation rule** if it satisfies

(i) Promise keeping: for all w_t and all t

$$\int_{\Theta} [(1 - \beta) f_t(w_t, \theta_t) \theta_t + \beta g_t(w_t, \theta_t)] d\mu = w_t$$

(ii) Truth telling: for all $z_t \in \Theta$, all $w_t \in D$ and all t

$$\begin{aligned} [(1 - \beta) f_t(w_t, \theta_t) \theta_t + \beta g_t(w_t, \theta_t)] d\mu \geq \\ [(1 - \beta) f_t(w_t, z_t) \theta_t + \beta g_t(w_t, z_t)] d\mu \end{aligned}$$

(iii) Boundedness: $\lim_{t \rightarrow \infty} \beta^t g_t(w_t(w_0, z^{*t-1}), z_t^*) = 0$

Planner's Problem

$$\min_{\sigma} y$$

subject to:

- σ is an allocation rule
- The allocations rule σ attains ψ with resources y

$$\int_{D \times \Theta} C(f_t(w_t, \theta)) d\mu(\theta) d\psi_t(w) \leq y \text{ for all } t$$

where for all t

$$\psi_{t+1}(w) = S_g(\psi_t)(w) \equiv \int_{D \times \Theta} I\{w_t : g_t(w_t, \theta) = w\} d\mu d\psi_t$$

Equivalence

Lemma 3.1 Let $\psi \in M$ and suppose the allocation u attains ψ with resources y . Then there is an allocation rule σ that attains ψ with resources y .

Lemma 3.2 Let $\psi \in M$. Suppose the allocation rule σ attains ψ with resources y and that u is the utility plan generated by σ . Then u is an allocation, and u attains ψ with resources y .

\implies We can work with allocation rules σ and then find the corresponding allocation u .

$$f_t(w_t(w_0, z^{t-1}), z_t) = u_t(w_0, z^t), g_t(w_t, z_t) = w_{t+1}$$

Planner's Problem

$$\min_{\sigma} y$$

subject to:

- σ is an allocation rule
- The allocations rule σ attains ψ with resources y

$$\max_t \left[\int_{D \times \Theta} C(f_t(w_t, \theta)) d\mu(\theta) d\psi_t(w) \right] \leq y$$

where for all t

$$\psi_{t+1}(w) = S_g(\psi_t)(w)$$

Bellman Equation

Let $\varphi^*(\psi)$ be the minimum cost of attaining a distribution ψ .

$$\varphi(\psi) = \inf_{f, g \in B} \max \left\{ \int_{D \times \Theta} C(f(w, \theta)) d\mu(\theta) d\psi(w), \varphi^*(S_g \psi) \right\}$$

where B is the set of all functions f, g such that they satisfy promise keeping and truth telling.

Problem T

Let X be the set of all functions $\varphi : M \rightarrow \mathbb{R}_+ \cup \{+\infty\}$. Define the operator $T : X \rightarrow X$ as

$$(T\varphi)(\psi) = \inf_{f,g \in B} \max \left\{ \int_{D \times \Theta} C(f(w, \theta)) d\mu(\theta) d\psi(w), \varphi(S_g \psi) \right\}$$

Lemma 4.1 φ^* is a fixed point of T

Problem T

Lemma 4.2 Suppose there are functions φ_a, φ_c and φ such that for all $\psi \in M$

- $\varphi_c < \varphi^* < \varphi_a$
- $\lim_{n \rightarrow \infty} T^n \varphi_a = \lim_{n \rightarrow \infty} T^n \varphi_c = \varphi$

Then, $\varphi = \varphi^*$.

Candidates:

- Autarky: $\varphi_a(\psi) = \int_D C(w) d\psi$
- Complete insurance: $\varphi_c(\psi) = \int_{D \times \Theta} C(u_c(w, \theta)) d\psi d\theta$, where $u_c(w, \theta)$ is the period utility an agent w with shock θ would receive if the shock was observable.

Example: log utility

- $V(x) = \log(x)$, $C(u) = \exp(u)$
- $D = \mathbb{R}$
- Bounding functions
 - $\varphi_a(\psi) = \int_D \exp(w) d\psi$
 - $\varphi_c(\psi) = \alpha \int_D \exp(w) d\psi$ where $\alpha = \exp\{-E[\theta \log \theta]\}$

Result: f, g linear in w and independent of ψ

- $f(w, \theta) = r(\theta; \alpha) + w$
- $g(w, \theta) = h(\theta; \alpha) + w$
 \implies Can choose r and h instead of f and g

Dynamics (log utility)

- Evolution of individual promised values:

$$w_t(w_0, \theta^{t-1}) = w_0 + \sum_{i=0}^{t-1} h(\theta_i; \alpha)$$

- Evolution of period utilities

$$u_t(w_0, \theta^t) = w_0 + \sum_{i=0}^{t-1} h(\theta_i; \alpha) + r(\theta_t)$$

⇒ Cross sectional variance

$$\text{Var} [w_t(w_0, \theta^{t-1})] = \text{Var}(w_0) + t\text{Var}[h(\theta; \alpha)]$$

$$\text{Var} [u_t(w_0, \theta^t)] = \text{Var}(w_0) + t\text{Var}[h(\theta; \alpha)] + \text{Var}[r(\theta)]$$

The degree of inequality grows without bound when resources are efficiently allocated.